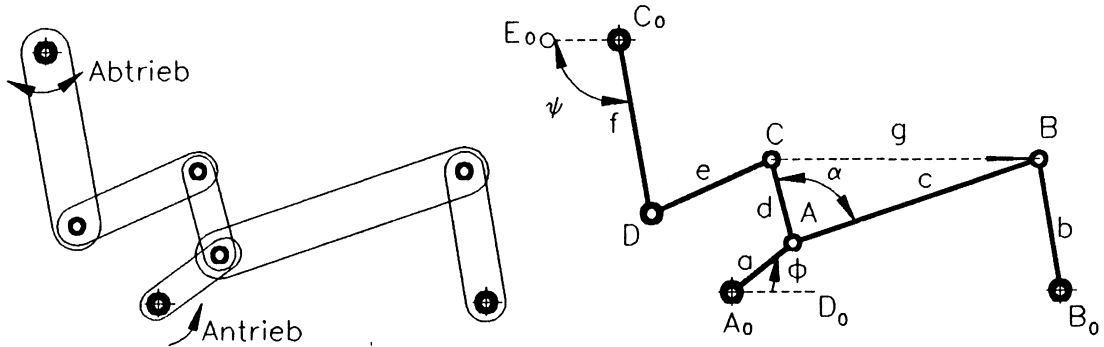
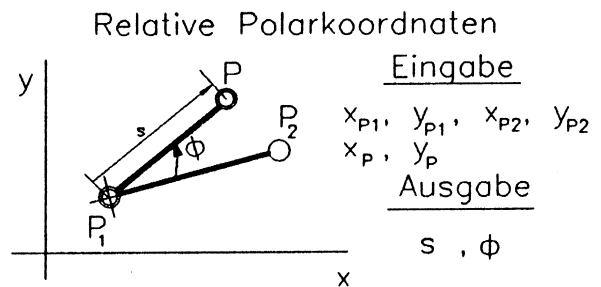
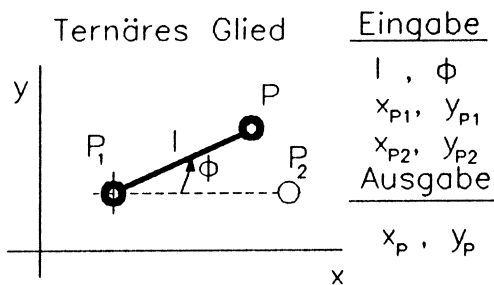
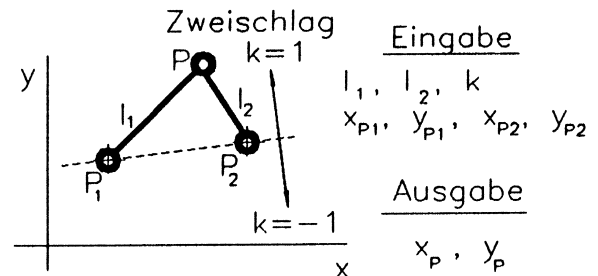
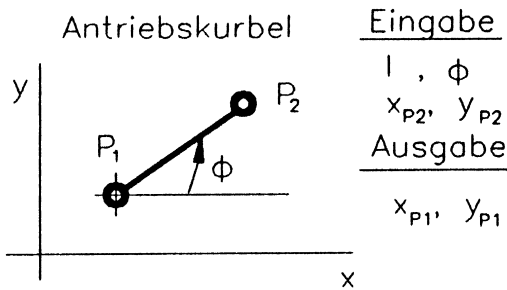


a. Getriebeaufbau und kinematisches Schema



b. Benötigte Berechnungsmodule



c. Rechengvorgang

Nr.	Module	Eingabe		Ausgabe
		Konstant	Variabel	
1	Antriebskurbel	a	$x_{A0}, y_{A0}, x_{D0}, y_{D0}, \phi$	$x_A, y_A$
2	Zweischlag	b, c, k	$x_A, y_A, x_{B0}, y_{B0}$	$x_B, y_B$
3	Ternäres Glied	d,	$x_A, y_A, x_B, y_B$	$x_C, y_C$
4	Zweischlag	f, e, k	$x_C, y_C, x_{C0}, y_{C0}$	$x_D, y_D$
5	Rel. Polarkoord.	-	$x_{C0}, y_{C0}, x_{E0}, y_{E0}, x_D, y_D$	$s_{C0D0}, \psi$